	ourse Title: SIGNAI					
Course Code	21EE51	Credits:4	CIE:	50		
Number of				50		
Lecture	3hrs (Theory)+	-2hrs. (Tutorials)	SEE:	SEE: 50		
Hours/Week						
Total Number of Lecture Hours		42	SEE Hou	rs: 03		
Prerequisite: 1. Knowledge of basic Analog si	anals is needed					
2. Knowledge of Laplace transfor		Differential equations				
Course Objectives:	mation, bolutions of I	Binerendar equations				
1. To study Definitions classifica	tion and basic operati	on of signals				
2. To understand time-domain re	-	-				
3. To know Fourier series represe	±					
4. To study Fourier and Z transfo		lications.				
<u> </u>	Modules		Te	aching		
				ours		
	Module I					
introduction: Definitions of sign	al and system, classif	ication of signals, basi	c operations	08 hrs		
on signals, elementary signals, a	and systems viewed a	as interconnections of	operations,			
properties of systems.						
	Module II					
Time Domain Representations	for LTI System: Co			08 hrs		
properties of impulse response	for LTI System: Correpresentation, diff			08 hrs		
	for LTI System: Correpresentation, diff			08 hrs		
properties of impulse response	for LTI System: Correpresentation, diff			08 hrs		
properties of impulse response representations, and block diagram	for LTI System: Correpresentation, diffus representation.	erential and differen	ce equation			
properties of impulse response representations, and block diagram Fourier Series Representation for	for LTI System: Correpresentation, diff ns representation. Module III or Signals: Introducti	erential and differen	ce equation	08 hrs 08 hrs		
properties of impulse response representations, and block diagram Fourier Series Representation for signal classes, orthogonality of	for LTI System: Correpresentation, diffus representation. Module III or Signals: Introduction Complex sinusoida	erential and differen	ce equation			
properties of impulse response representations, and block diagram	for LTI System: Correpresentation, difference of the second secon	erential and differen	ce equation			
properties of impulse response representations, and block diagram Fourier Series Representation for signal classes, orthogonality of continuous-time –series representa	for LTI System: Correpresentation, difference of the second secon	erential and differen on, Fourier representat l signals, DFTS rep	ions for four resentations,			
properties of impulse response representations, and block diagram Fourier Series Representation for signal classes, orthogonality of continuous-time – series representa	for LTI System: Correpresentation, difference of the second secon	erential and differen on, Fourier representat l signals, DFTS rep Courier Representati	ions for four resentations, ons: DTFT	08 hrs		
properties of impulse response representations, and block diagram Fourier Series Representation for signal classes, orthogonality of continuous-time –series representations Fourier Transformations and representations, properties of re-	for LTI System: Correpresentation, difference of the second structure of the s	erential and differen on, Fourier representat l signals, DFTS rep Fourier Representati lency response of L	ce equation ions for four resentations, ons: DTFT TI systems,			
properties of impulse response representations, and block diagram Fourier Series Representation for signal classes, orthogonality of continuous-time – series representations Fourier Transformations and representations, properties of re- solution, of differential and differ	for LTI System: Correpresentation, difference equation difference constraints of the system of the s	erential and differen on, Fourier representat l signals, DFTS rep Fourier Representati ency response of L system function, Fouri	ce equation ions for four resentations, ons: DTFT TI systems, er transform	08 hrs		
properties of impulse response representations, and block diagram Fourier Series Representation for signal classes, orthogonality of continuous-time –series representations Fourier Transformations and representations, properties of re- solution, of differential and differ representations for periodic sign	for LTI System: Correpresentation, difference equation difference construction.	erential and differen on, Fourier representat l signals, DFTS rep Fourier Representati ency response of L system function, Fouri	ce equation ions for four resentations, ons: DTFT TI systems, er transform	08 hrs		
properties of impulse response representations, and block diagram Fourier Series Representation for signal classes, orthogonality of continuous-time –series representations Fourier Transformations and representations, properties of re-	for LTI System: Correpresentation, difference equation of the second sec	erential and differen on, Fourier representat l signals, DFTS rep Fourier Representati ency response of L system function, Fouri	ce equation ions for four resentations, ons: DTFT TI systems, er transform	08 hrs		
Fourier Series Representation for signal classes, orthogonality of continuous-time –series representations Fourier Transformations and representations, properties of re- solution, of differential and differ representations for periodic sign reconstruction.	for LTI System: Correpresentation, difference of the second secon	erential and differen on, Fourier representat l signals, DFTS rep Fourier Representati ency response of L system function, Fouri ntinuous time signals	ce equation ions for four resentations, ons: DTFT TI systems, er transform and signal	08 hrs		
Fourier Series Representation for signal classes, orthogonality of continuous-time – series representations Fourier Transformations and representations, properties of re- solution, of differential and differ representations for periodic sign reconstruction.	for LTI System: Correpresentation, difference of the second structure of the s	on, Fourier representat on, Fourier representat l signals, DFTS rep Fourier Representati ency response of L system function, Fouri ntinuous time signals of ROC, properties Z	ce equation ions for four resentations, ons: DTFT TI systems, er transform and signal Z- transform,	08 hrs		
Fourier Series Representation for signal classes, orthogonality of continuous-time –series representations and representations, properties of re- solution, of differential and differ representations for periodic sign reconstruction. Z-Transforms: Introduction, Z- inverse transformation, analysis of	for LTI System: Correpresentation, difference of the second secon	on, Fourier representat on, Fourier representat l signals, DFTS rep Courier Representati tency response of L system function, Fouri ntinuous time signals of ROC, properties Z fer function, stability a	ce equation ions for four resentations, ons: DTFT TI systems, er transform and signal Z- transform,	08 hrs 10 hrs		
Fourier Series Representation for signal classes, orthogonality of continuous-time – series representations and the series representations and representations, properties of re- solution, of differential and differ representations for periodic sign reconstruction. Z-Transforms: Introduction, Z- inverse transformation, analysis of unilateral Z-transform and its app	for LTI System: Correpresentation, difference of the second structure of the s	erential and differen on, Fourier representat l signals, DFTS rep Fourier Representati ency response of L system function, Fouri ntinuous time signals of ROC, properties Z er function, stability a equation.	ce equation ions for four resentations, ons: DTFT TI systems, er transform and signal C- transform, nd causality,	08 hrs 10 hrs 08 hrs		
Fourier Series Representation for signal classes, orthogonality of continuous-time –series representations Fourier Transformations and representations, properties of re- solution, of differential and differ representations for periodic sign reconstruction. Z-Transforms: Introduction, Z- inverse transformation, analysis of unilateral Z-transform and its app Question paper pattern: Total te	for LTI System: Correpresentation, difference of the second structure of the s	on, Fourier representation on, Fourier representation on, Fourier Representation fourier Representation of ROC, properties Z of ROC, properties Z for function, stability a equation.	ce equation ions for four resentations, ons: DTFT TI systems, er transform and signal C- transform, nd causality,	08 hrs 10 hrs 08 hrs		
properties of impulse response representations, and block diagram Fourier Series Representation for signal classes, orthogonality of continuous-time – series representations Fourier Transformations and representations, properties of re- solution, of differential and differ representations for periodic sign reconstruction. Z-Transforms: Introduction, Z- inverse transformation, analysis of unilateral Z-transform and its app Question paper pattern: Total te answer five questions, selecting at	for LTI System: Correpresentation, difference of the second structure of the s	on, Fourier representation on, Fourier representation on, Fourier Representation fourier Representation of ROC, properties Z of ROC, properties Z for function, stability a equation.	ce equation ions for four resentations, ons: DTFT TI systems, er transform and signal C- transform, nd causality,	08 hrs 10 hrs 08 hrs		
properties of impulse response representations, and block diagram Fourier Series Representation for signal classes, orthogonality of continuous-time –series representations Fourier Transformations and representations, properties of re- solution, of differential and differ representations for periodic sign	for LTI System: Correpresentation, difference equation using shals, sampling of correspondence of LTI systems, transform, properties of LTI systems, transform will be as a least one from each the system of the sy	on, Fourier representat on, Fourier representat l signals, DFTS rep Fourier Representati ency response of L system function, Fouri ntinuous time signals of ROC, properties Z er function, stability a <u>equation.</u> ked. Two from each n module.	ce equation ions for four resentations, ons: DTFT TI systems, er transform and signal C- transform, nd causality, hodule. The stude	08 hrs 10 hrs 08 hrs		
properties of impulse response representations, and block diagram Fourier Series Representation for signal classes, orthogonality of continuous-time –series representations Fourier Transformations and representations, properties of re- solution, of differential and differ representations for periodic sign reconstruction. Z-Transforms: Introduction, Z- inverse transformation, analysis of unilateral Z-transform and its app Question paper pattern: Total te answer five questions, selecting at Reference Books:	for LTI System: Correpresentation, difference equation using shals, sampling of correspondence of LTI systems, transform, properties of LTI systems, transform will be as a least one from each the system of the sy	on, Fourier representat on, Fourier representat l signals, DFTS rep Fourier Representati ency response of L system function, Fouri ntinuous time signals of ROC, properties Z er function, stability a <u>equation.</u> ked. Two from each n module.	ce equation ions for four resentations, ons: DTFT TI systems, er transform and signal C- transform, nd causality, hodule. The stude	08 hrs 10 hrs 08 hrs		
properties of impulse response representations, and block diagram Fourier Series Representation for signal classes, orthogonality of continuous-time –series representations Fourier Transformations and representations, properties of re- solution, of differential and differ representations for periodic sign reconstruction. Z-Transforms: Introduction, Z- inverse transformation, analysis of unilateral Z-transform and its app Question paper pattern: Total te answer five questions, selecting at Reference Books: 1. Simon Haykin and Barry Van V	for LTI System: Correpresentation, difference in the second strength of the second strengt	on, Fourier representation on, Fourier representation of ROC, properties Z of ROC, properties Z for function, stability a equation. ked. Two from each m module.	ce equation ions for four resentations, ons: DTFT TI systems, er transform and signal Z- transform, nd causality, nodule. The studes	08 hrs 10 hrs 08 hrs		

- 3. Signal and Systems by Uday kumar. Elite Publishers, 2004
- 4. Michel J Roberts, "Signal and Systems: Analysis through linear system", TMI, 2003.
- 5. Alan V.Oppenheim, Alan S Willsky and S. Hamid Nawab, "Signal and Systems", pearson Eduction Asia, 2nd Edition, 1997. Indian.

Course outcomes	:						
On completion of the course, the student will have the ability to:							
Course Code	CO	Course Outcome (CO)					
	CO1	Classify different continuous and discrete signals					
	CO2	Illustrate the time domain representation for Linear Time Invariant					
		systems					
16EE54	CO3	Analyze the fourier series and fourier transformation for discrete and					
		continuous signals					
	CO4	Apply the fourier series and fourier transformation for LTI system					
	CO5	Illustrate fourier transform and Z-transform					

Course Articulation Matrix for the Academic Year 2021-22

S.No.	PO	1	2	3	4	5	6	7	8	9	10	11	12	PSO1	PSO2	PSO3
	CO															
1	CO1	3	3	3									1	3		1
2	CO2	3	3	3									1	3		1
3	CO3	3	3	3									1	3	1	1
4	CO4	3	3	3	1								1	3	1	1
5	CO5	3	3	3									1	3		1
		3	3	3	1								1	3	1	1

C	ER						
Course Code	21EE52	Credits:04		CIE: 50			
Number of Lecture Hours/Week	3 hrs.(Theory) -		SEE: 50				
Total Number of Lecture Hours	2	SE	E Hours: 03				
 Prerequisite: 1. Knowledge of Digital Ele 2. Knowledge of Signal and 3. Knowledge of Microproce Course Objectives: 1. To study architecture of 8 	system subject i essors and its app 051 family.	s needed lications.					
 To understand about instr To know about different ty To study I/O port interfact 							
5. To understand interfacing	Teaching Hours						
Introduction: Overview of modes, Registers, External M Instructions and Program and Call instructions and Pro	-	09 Hours					
	Module II						
External hardware interru	Interrupts: Counters and Timers, 8051 Interrupts, Timer interrupts, External hardware interrupts, Serial communication interrupts and Interrupts priority and its Programming.						
	Module III						
I/O Port Interfacing : I/O pr Keyboard Interfacing.	ogramming, AD	C, DAC, LCD, Ste	pper motor	08 Hours			
	Module IV						
Interfacing to External M address decoding, Interface	pace.	08 Hours					
Interfacing to the Progr Interfacing and its programm Arm 32-Bit Microcontrol ARM, Architecture of ARI techniques, registers and interfacion	ication of	08 Hours					

Question paper pattern: Two questions from each module will be set. The student has to answer five full questions, selecting at least one full question from each module.

Reference Books:

1. Muhammad Ali Mazidi & Janice Gillespie Mazidi: 8051 Controller and Embedded Systems – Pearson Education, Second edition, 2008.

2. Kenneth . J. Ayala: The 8051 Microcontroller Architecture, Programming and Application, 2E, Pen Ram International, 1991.

3. Predko: Programming and Customizing the 8051 Microcontroller" TMH, 2008.

4. Raj Kamal: Microcontroller: Architecture, Programming Interfacing and Systems Design" Pearson Education,2009.

5. Andrew N. Sloss, Dominic Symes, Chris Wright, "ARM Systems Developer's Guides- Designing & Optimizing System Software", 2008, Elsevier

Course outcomes:

On completion of the course, the student will have the ability to:

Course Code	CO	Course Outcome (CO)	
	CO1	Describe the architecture and operation of 8051 microcontroller	
	CO2	Apply the knowledge of instruction set & addressing modes for writing programs	
21EE52	CO3	Use of timer & Interrupts through programs	
	CO4	Discuss the different applications such as ADC, DAC, LCD & develop the programs for interfacing.	
	CO5	Experiment I/O and memory interfacing	
	CO6	Develop the program and interfacing of 8255	

S.No.	PO	1	2	3	4	5	6	7	8	9	10	11	12	PSO1	PSO2	PSO3
	CO															
1	CO1	3											1	3		
2	CO2	3	2										1	3	2	2
3	CO3	3		2									1	3	2	2
4	CO4	3		1									1	3	2	2
5	CO5	3											1	3	2	2
6	CO6	3											1	3	2	2
		3	2	1.5									1	3	2	2

Course Title: POWER SYSTEM ANALYSIS AND STABILITY									
Course Code	21EE53	Credits:03		CIE: 50					
Number of Lecture									
Total Number of Lecture Hours	2	SE	E Hours: 03						
Prerequisite: Knowledge of Knowledge of Electrical Ma		Distribution							
Course Objectives: 1. To study power syste 2. To analysis different 3. To Calculate balance 4. To understand the co	es in power em network	•							
Representation of Power transmission line, synchrono diagram, calculation of per	single line dance and	8Hrs							
reactance diagram, advantag Symmetrical Three Phase	Module II								
line, short-circuit currents a no load and load condition, using Thevenin's theorem, S	current oscillogra	ms. Analysis of sh		8Hrs					
	Module III								
Symmetrical Components symmetrical components a components passing throug Analysis of balanced and ur three phase supply. Sequen system elements. (Alternato negative and zero sequence n	8Hrs								

		Module IV					
Unsymmetrical Faults: Single line to ground (L-G), line to line (L-L), Double line to Ground (L-L-G) faults on unloaded alternator with and without fault impedance. Unsymmetrical faults on a power system with and without fault impedance. Open conductor faults in power systems.							
		Module V					
machine, const Stability studie	ant M and H s, steady sta ic stability, e	amics and the swing equation of synchronous of rotating machines, Power angle equation, ate stability and pull out curve. Transient equal-area criterion of stability studies and its g on stability.	9Hrs				
	-	tal ten questions will be asked. Two from each estions, selecting at least one from each module					
Reference Bool	ks:						
edition. 2003 2. W.D. Stevens Revised edition 3. Power system 4. Computer Aid	on," Element (1 Septembe analysis by l led PSA, GL	ari, "Modern power system analysis", Tata Mcg s of power system analysis", McGraw Hill Hig r 1982) hadi sadat, TMH. 3rd Edition, 2011. Kusic, PHI.3rd Edition 2010 d stability by Neelakantan. 2013 Edition.					
Course outcom	•						
		e, the student will have the ability to:					
Course Code	CO	Course Outcome (CO)					
	CO1	Illustrate power system network with its basic knowledge					
21EE53	CO2	Identify the different types of faults in power system network.					
	CO3	Calculate power of balanced and unbalanced load					
	CO4	Analyze the short circuit studies in power system network					
	CO5	Examine the stability concept in power system engineering					

S.No.	PO	1	2	3	4	5	6	7	8	9	10	11	12	PSO1	PSO2	PSO3
	CO															
1	CO1	3	3	1									2	3	2	1
2	CO2	3	3	1	1		2						2	3	2	2
3	CO3	3	3	3	1								2	3	2	2
4	CO4	3	3	3	1								2	3	2	2
5	CO5	3	3	1	1								2	3	2	2
		3	3	1.8	1		2						2	3	2	1.8

(Course Title: POV	WER ELECTRONIC	S		
Course Code	21EE54	Credits: 03	CII	E: 50	
Number of					
Lecture	2hrs (Theory	/)+2(Tutorial)	SEE	E: 50	
Hours/Week					
Total Number of Lecture Hours	2	SEE H	ours: 03		
Prerequisite:					
1. Digital electronics					
2. Knowledge of Electronic Circu	uit is needed				
Course Objectives:					
1. To study Power MOSFET's IG	BT.				
2. To understand Thyristors, GTO	s and Commutation	on Techniques.			
3. To know about AC Voltage Co	ntrollers & Contro	olled Rectifiers.			
4. To understand the use and App	lication of DC Ch	oppers.			
	Modules			Teaching Hour	
	Module I				
Power MOSFETs & Insulated	Gate Bipolar Tra	ansistors (IGBTs):			
Power MOSFETs Junction Struc Safe Operating Area (SOA), Gat Times.				09 hrs	
Insulated Gate Bipolar Transist and power BJT, Junction Structur Drive Requirements, Switching T	re, Principle of W	1 1			
	Module II				
Thyristors & The Gate Turn Of	f Thyristor (GT	D):			
Thyristors Characteristics, Two- Thyristor. Turn off, Series open di/dt Protection, dv/dt Protection.		• •		08 hrs	
The Gate Turn Off Thyristor (G Short GTO. GTO Switching chara		tructures of Symmetri	cal and Anode		

Module III	
Commutation Techniques & AC Voltage Controllers:	
Introduction, Natural commutation, Forced commutation, self commutation, impulse commutation.	08 hrs
AC Voltage Controllers: Introduction, Principle of ON-OFF and Phase Control. Single-phase bidirectional controllers with resistive and inductive loads.	
Module IV	
Controlled Converters:	
Introduction principle and operation of Phase controlled converter and operation. Single phase converters, Full converters. Three-phase full-wave converters.	09 hrs
PWM Inverters: Introduction, principle of operation, performance parameters, single phase bridge inverters, voltage control of single phase inverters, Three phase inverter (120 and 180 degree conduction mode)	
Module V	
DC Choppers:	
Introduction, principle of step-down and step-up chopper with R and R-L load, Performance parameters. Chopper classification.	08 hrs
Question paper pattern: Total ten questions will be asked. Two from each module. The answer five questions, selecting at least one from each module.	e student has to
Reference Books:	
1. Power Electronics, M.H. Rashid 3rd Edition, P.H.I. / Pearson, New Delhi, 2006	
2. "Power Electronics –Converters, Applications and Design", Ned Mohan, Tore M. Und P.Robins, Third Edition, John wjley and sons.1989	eland, and William
3. Power Electronics circuit, Devices and applications. Rashid PHI, Third Edition 2013	
4. Joseph Vithayathil "Power Electronics Principles and Applications" (Edition 2010)	
3. Power Electronics circuit, Devices and applications. Rashid PHI, Third Edition 2013	

Course outcomes	:						
On completion of the course, the student will have the ability to:							
Course Code	СО	Course Outcome (CO)					
	CO1	Illustrate the working of specified power electronic devices – MOSFET, IGBT, GTO, SCR. C3					
21EE54	CO2	Analyze natural and forced commutation techniques.					
	CO3	Assess AC voltage controllers at resistive and inductive loads.					
	CO4	Analyze controlled rectifier for single and three phase converters for resistive and inductive loads.					
	CO5	Analyze and categorize DC choppers.					

S.No.	PO	1	2	3	4	5	6	7	8	9	10	11	12	PSO1	PSO2	PSO3
	CO															
1	CO1	3	1	2									1	3	3	1
2	CO2	3	1	2									1	3	3	1
3	CO3	3	1	2									1	3	3	1
4	CO4	3	3	2									1	3	3	1
5	CO5	3	3	2									1	3	3	1
		3	1.8	2									1	3	3	1

	C	ourse T	Title: POWER E	LECTRONICS	LAB							
	Course Code		21EEL55	Credits:01	CIE: 50							
	Number of Lecture Hours/Week		2hrs (P	SEE: 50								
Total Nu	mber of Lecture H	ours			SEE Hours: 03							
Sl.No.			List of Experiments									
1	Static characteri	stics of	of SCR.									
2	Static character	stics o	f MOSFET									
3	Static characteri	stics IC	GBT.									
4	SCR turn-on cire	cuit usi	ng synchronized	UJT relaxation o	scillator							
5	SCR Digital trig	gering	circuit for a singl	le-phase controlle	ed rectifier / A.C voltage							
6		l-wave	e rectifier with R and R-L loads.									
7	A.C. voltage controller using TRIAC and DIAC combination connected to F loads.											
8	DC-Chopper wi	h RL l	oad.									
9	Single phase con	verter	R load.									
10	3-φ controlled re											
<u>11.</u> 12.			e Inverter with R									
	itcomes: On comp	-	e inverter with R of the course, th		ve the ability to:							
			······································									
Course Co	ode CC)	Course	e Outcome (CO)								
	СО		scribe static ctronic devices.	characteristics	of power							
19EE56	CO	rel	periment to (axation oscillato) voltage of AC v	te the RMS								
	CO	3 Ca	lculate the DC o	/p voltage of cho	opper.							
	СО		lculate the avo ntrolled convert	e i								
	СО		lculate the ave ntrolled convert		•							

S.No.	PO	1	2	3	4	5	6	7	8	9	10	11	12	PSO1	PSO2	PSO3
	CO															
1	CO1	3			1					2			1	3	1	1
2	CO2	3			1					2			1	3	1	1
3	CO3	3			1					2			1	3	1	1
4	CO4	3			1					2			1	3	1	1
5	CO5	3			1					2			1	3	1	1
		3			1					2			1	3	1	1

Co	urse Title: COMPUTER APPLI SYSTEM	CATIONS TO POWER								
Course Code	50									
Number of Lecture Hours/Week	Lecture02hrs.(Theory)SEE:Hours/Week+ 02(Tutorial)otal Number of42									
Total Number of Lecture Hours	42 SEE Hours: 03									
	Credit:	03								
2. Power System Stabi	• •									
 To understand differe To Study and analysi To understand econo 	t methods of Admittance bus of ent types of buses and its analysi s of transient stability systems. mic concept of power systems. voltage control method for pow	s using load flow study.								
•	Modules	-	Teaching Hours							
incidence matrices: Element node incidence impedance & admittance	Module I a power system network by di matrix, Bus incidence matrix, Pr form, primitive {y} matrix. For nethod, Algorithm for formation e basis.	imitive network in mation of Y-bus by	08hrs							
flow equations, solution Newton Raphson method LF solution by Fast-deco	Module II g constraints, Classification of sy of load flow equations by Gauss l, Acceleration of convergence upled method. Comparison of L anging & phase shifting transfor	-Seidel method, and F methods,	09hrs							
studies, load representation with flow charts. Transie	Module III ly: tation of synchronous machine f on network performance equation nt stability solution by numericated odified Euler's method, Runge-K	n, solution techniques Il solution of	08hrs							

		Module IV						
between plants in	es, load	Power Systems. sharing between the units within plants, load sharing transmission losses. Penalty factor, Derivation of and loss coefficient, hydrothermal constraints. Module V	08hrs					
Automatic load fr (AVR), loop diagonal system Generator ALFC Block diagonal	Automatic Generation & Voltage control: Automatic load frequency control (ALFC) and Automatic voltage regulator (AVR), loop diagrams Automatic load frequency control for fly ball governing system Generator model. Load model, turbine model. governor model complete ALFC Block diagrams steady state and dynamic response of ALFC loops single area and two area block diagram representation.							
	•	Total ten questions will be asked. Two from each modul	e. The student has					
to answer five que Reference Books		selecting at least one from each module.						
Edition 1968. 2. M.A. Pai " Con 3. Nagrath & Kot 4. Uma Rao, "Con 5. L.P. Singh, "Ac International Pvt.] 6. R.N. Dhar, "con 7. Hadi sadat, "Po 8. Elgerd, "Electri Course outcomes On completion o	nputer T hari, "M mputer T dvanced Ltd, Nev mputer A ower syst ic Energ s: f the cou	Aided Power System Operations & Analysis", TMH 1984 tem Analysis", TMH, 2nd Edition, 12th Reprint 2007. y Systems Theory", TMH, 1983. Trse, the student will have the ability to:	lition 2006. Edition 2003. Pvt.Ltd, New Age					
Course Code	CO #	Course Outcome (CO)						
21EE61	CO1	Describing the Y-bus formation in power system network th inspection method.	rough matrices and					
	CO2	Calculation of Voltage magnitude and power in a power syst	tem network.					
	CO3	Relate various load flow method in power system network.						
	CO4	Analyse the transient stability and Economic operation of po	ower systems.					

Course Articulation Matrix for the Academic Year 2022-23

S.No.	РО	1	2	3	4	5	6	7	8	9	10	11	12	PSO1	PSO2	PSO3
	СО															
1	CO1	3	3		2	1							1	3	1	1
2	CO2	3	3		2	1							1	3	2	1
3	CO3	3	3		2	1							1	3	2	1
4	CO4	3	3		2	1							1	3	2	1
5	CO5	3	3		2	1							1	3	2	1
		3	3		2	1							1	3	2	1

Course '	Title: SWITCH	GEAR AND PRO	DTECTION	
Course Code	21EE62	Credit: 04	C	CIE: 50
Number of Lecture Hours/Week		(Theory) + (Practical)	SI	EE: 50
Total Number of Lecture Hours		42	SEE	Hours: 03
Course Objectives:				
 Switches, fuses, MCB a Functioning of circuit be Characteristics and funce Apparatus protection 	reaker	resters		Teaching Hours
Switches and Fuses: Introduced finition of switchgear. Types off characteristics, time current fuse, application of fuse, MCB Lightning Arresters: Causes different types of lightning arresters.	08 Hrs			
Circuit Breakers: Introductio preakers. Comparison betweer properties, initiation and main palance theory for Arc interrup rise of Restriking Voltage, De chopping, capacitance switch preakers.	n an isolator an tenance of an a tion. Restriking C circuit breaki	d circuit breaker, rc, Slepian's the voltage, recovery	phenomenon, ory and energy voltage, Rate of eaking, current	09 Hrs
	Module – III			
Types of Circuit Breakers: circuit breakers, Oil circuit br OCB, SF ₆ breaker – Preparatic breakers. Vacuum circuit brea details. Advantages and disad comparison of different circ Breakers.	reak, minimum fer type of SF_6 constructional ircuit breakers,	08 Hours		
Testing of Circuit Breakers: Compensation test and Capacita		ynthetic testing, So	ubstitution test,	
	Module – IV			
Protective Relaying: Requiren primary and backup protection Classification of Protective Relation	on, Essential q	• •	-	09 Hrs

IDMT and Directional characteristics, Differential relay- Principle of operation, percentage differential relay, bias characteristics, distance relay – Three stepped distance protection, Impedance relay, Reactance relay , Mho relay, Buchholz relay, Microprocessor based over current relay – block diagram approach. Module- V Protection Schemes: Principles and need for protective schemes, Zones of Protection. Transformer Protection: Differential protection, differential relay with harmonic restraint, Inter turn faults. Generator Protection: Merz price protection, prime mover faults, stator and rotor faults, protection against abnormal conditions - unbalanced loading, loss of excitation, over speeding. Bus bars and Transmission Line Protection: Introduction, bus bar protection, frame leakage protection, differential protection, distance protection, three zones protection	08 Hrs
Question paper pattern: Total ten questions will be asked. Two from each modul	e. The student has
to answer five questions, selecting at least one from each module.	

- 1. Switchgear & Protection, Sunil S. Rao., Khanna Publishers, 13th Edition, 2008
- 2. Power System Protection & Switchgear. Badriram & Viswa Kharma, TMH, 1st Edition 2001.
- 3. Fundamentals of Power System protection, Y.G. Painthankar and S R Bhide, PHI, 2009
- 4. Power System Protection and Switchgear, B. Rabindranath and N. Chandra, New Age International (P) Ltd. 1st Edition 2011.

Reference Books:

- 1. Electrical Power Systems, C.L.Wadhwa, 6th Edition, New Age International(P) Ltd. 2010
- 2. A Course in Electrical Power, Soni Gupta & Bhatnagar, Dhanapatirai.
- 3. Electrical Power, Dr. S.L.Uppal, Khanna Publications.

Course outcomes:

On completion of the course, the student will have the ability to:

Course Code	СО	Course Outcome (CO)	
	CO1	Discuss different types of protection devices used in power system: switches, fuses, MCB, Lightning Arresters	
21EE62	CO2	Describe the principles of circuit breaker	
	CO3	Describe different types of circuit breaker, Suggest suitability circuit breaker, testing of circuit breaker	
	CO4	Understand and analyze electromagnetic relays	

CO5	Find the causes of abnormal operating conditions of the apparatus and system.	
CO6	Discuss different types of protection devices used in power system: switches, fuses, MCB,	
	Lightning Arresters	

S.No.	PO	1	2	3	4	5	6	7	8	9	10	11	12	PSO1	PSO2	PSO3
	CO															
1	CO1	3					2						2	3	2	1
2	CO2	3					2						2	3	2	1
3	CO3	3					2						2	3	2	1
4	CO4	3					2						2	3	2	1
5	CO5	3					2						2	3	2	1
		3					2						2	3	2	1

Course	e Title: SIGNA	ALS AND SYST	TEMS						
Course Code	21EE64X	Credits:03		CIE: 50					
Number of									
Lecture	•	ory)+2hrs. orials)		SEE: 50					
Hours/Week									
Total Number of Lecture Hours	4	2	SE	E Hours: 03					
Prerequisite: 1. Knowledge of ba	sic Analog sign	als is needed							
2. Knowledge of Laplace transfo	ial equations								
Course Objectives									
5. To study Definitions classification	ation and basic o	peration of signa	ls.						
	6. To understand time-domain representation for LTI systems.								
 To know Fourier series representation To study Fourier and Z transfer 									
	Teaching Hours								
]	Module I								
Introduction: Definitions of signal ar	hasic								
operations on signals, elementary sig	-	-	, busic						
interconnections of operations, prop	-			08 hrs					
I	Module II								
Time Domain Representations for L	FI System: Convo	olution, impulse							
representation, properties of impuls	e response repre	sentation, differe	ential and						
difference equation representations,	and block diagra	ams representation	on.	08 hrs					
Ν	Iodule III								
Fourier Series Representation for Sig	gnals: Introductio	on, Fourier repre	sentations						
for four signal classes, orthogonality	ГS								
representations, continuous-time -s	eries representat	tions		08 hrs					
Ν	Iodule IV								
Fourier Transformations and Applications properties of representations, properties of representations, solution, of differential and Fourier transform representations for time signals and signal reconstruction	f LTI function,	10 hrs							

		Module V								
Z-Transforms: Introduction, Z- transform, properties of ROC, properties Z- transform, inverse transformation, analysis of LTI systems, transfer function, stability and causality, unilateral Z-transform and its application to difference equation. 08 hrs										
• • • •		ten questions will be asked. Two from each ecting at least one from each module.	module. The student							
Reference Books:										
1. Simon Haykin	and Barry Van	Veen, "Signal and Systems", John Willey and Sir	IS,							
2001. Reprint	2002.									
2. Signal and Sys	stems by Ganes	h Rao and Satish Tonga. 3 rd Edition, Sanguine								
Technical Pub	lishers, 2005.									
3. Signal and Sys	stems by Uday I	kumar. Elite Publishers, 2004								
4. Michel J Robe	erts, "Signal and	Systems: Analysis through linear system", TMI,								
2003.										
5. Alan V.Oppen	heim, Alan S W	'illsky and S. Hamid Nawab, "Signal and Systems	n ,							
pearson Educt	tion Asia, 2 nd Ec	lition, 1997. Indian.								
Course outcomes:	:									
On completion of	the course, th	ne student will have the ability to:								
Course Code	CO #	Course Outcome (CO)	Blooms Level							
21EE64X	CO1	Define and classify different types of signals	C1							
	CO2	Interpret the time domain	C2							

representation for LTI systems

Analyze the Fourier series and Fourier transformation for discrete

transformation for LTI system

Apply the Fourier series and Fourier

Illustrate Fourier transform and Z-

and continuous signals

transform

C4

C4

C2

CO3

CO4

CO5

Control Systems										
Subject code:22EE641	Credits:04	Total hours:42								
CIE:50 marks	SEE:50 Marks	SEE:03hrs								
	3hrs.(Theory)+ 2hrs.(Practica									

Objectives of overall learning of the subject:

1. To study open -loop and closed -loop control system

2. To understand mathematical modelling of system.

3. To study the block diagram and signal flow graph reduction techniques.

4. To know and study time-response control systems and stability analysis of control system.

5. To understand frequency response and root locus analysis of control systems.

6. To understand the state variable and analysis.

MODULE -I

Physical Systems modelling:-Basic definitions of control systems, requirements of control systems, classification of control systems, and comparison of open loop and closed loop systems. Effect of feedback on closed loop systems. Modelling of basic mechanical & electrical components, modelling of mechanical, electrical and electromechanical systems using Laplace transform and differential equations, Analogous systems.

To Study the MATLAB Package for simulation of control system design 08 hrs

MODULE -II

Block Diagram Reduction Techniques: Block diagram representations, development of block diagram, reduction techniques to obtain over all transfer function using Block diagram Algebra. Signal flow graph and its properties, Mason's gain formula and its applications. To Reduce Linear Systems Block Diagram Using Series, Parallel And Feedback Configuration using MATLAB 08 hrs

MODULE -III

<u>Time Response & Stability Analysis</u>: Time response, transient and steady state response of first order and second order systems for unit step input, Time domain specifications for second order systems. Classification of stability, BIBO stability, R-H criterion for stability Analysis and its special cases.

To verify the output response of a Second Order System using RLC circuit. 08 hrs

MODULE – IV

Root Locus & Frequency Domain Analysis: Root Locus, General rules to construction of root locus diagram, stability analysis using root locus. Frequency domain specifications, co-relation between time – domain & frequency domain specifications, Bode plot, Stability analysis. Polar plot, Nyquist stability, Nyquist plot, stability Analysis.

To analyze frequency response of a system by plotting Root locus, Bode plot and Nyquist plot using MATLAB software. 09 hrs

MODULE –V

<u>State variable Analysis:</u> Concepts of state variables, State space model, Diagonalization of State Matrix, Solution of state equations, Eigen values and Stability Analysis, Concept of controllability and observability. Difference Equations of time domain system. State-space models of linear discrete-time systems, Stability of linear discrete-time systems.

To develop state space model for a transfer function using MATLAB 09 hrs

Question Paper Pattern: Answer five full Questions selecting one full question from each module.

Course Out comes: At the end of the course student will able to

- CO1: Explain basic terminologies of control system & mathematical modeling. C2
- CO2: Analyze block diagram and signal flow graphs reduction techniques.C4
- CO3: Use stability and time response analysis.C2

CO4: Explain Root Locus, analysis frequency response, frequency domain stability. C5 CO5: Explain basic state variables and state space models. C2

Text/Reference books:

- 1. Control system Engg, I.J. Nagrath & M Gopal, 5th edition New-Age Publications.
- 2. Control Engg: Theory and Practice: B N Bandyopadhaya, PHI Publications.
- 3. Control systems: Ashfaq hussain and Haroon Ashfaq, Dhanpat Rai and co.
- 4. Automatic control systems B.C. KVO PHI publications VII edition.
- 5. Control system Engg palani Mcaraw hill publications.
- 6. A Text books of Automatic control system Engg, Dr. N.K Joain, Dhanpat rai & co.
- 7. B. C. Kuo, "Automatic Control System", Prentice Hall, 1995.
- 8. K. Ogata, "Modern Control Engineering", Prentice Hall, 1991.

Course Code	21EEL66	CIE: 50											
Number of													
Lecture	2hrs.(Theory)	SEE: 50											
Hours/Week	Credits: 01												
Total Number of Lecture Hours	42	SEE Hours: 03											
	Modules	Teaching Hours											
MATLAB													
1. MATLAB fundamenta	als, matrices, Vectors, matrix and array op	perations.											
2. Using built in function	is, saving and loading data, script files.												
3. Function files, language	ge specific features much as loops, branch	es and control flow.											
Power system simulatio	n using MATLAB, software packages a	and C++											
1. i) Y-Bus formation for transformation and inspe	systems with and without mutual couplination method.	ng, by singular											
ii) Determination of Bus bus profile.	currents, bus power & line flows for a spe	ecified system voltage											
2. ABCD parameters													
i) Formation for symmetr	ric π/T configuration												
ii) Verification of AD-BO	C=1												
III) Determination of effi	iciency and regulation												
	er angle diagrams for salient and nonsalie ver, excitation emf and regulation.	nt pole synchronous											
	rents and voltages in a single transmission pecified location for SLGF, DLGF, and L	•											
connected to infinite bus	ve i) swing curve ii) critical clearing time through a pair of identical transmission li tion of inertia constant/line parameters/fau	ines. for a 3-phase on											
6. Load flow analysis for iterations (Y-bus to be gi	a 3 Bus system using Gauss Seidal meth ven as data)	od for at least 3											
7. Formation of jacobian ordinates.	for a system not exceeding 4 buses (no P	V buses) in polar co-											

		tem, computation of Jacobian to conduct load flow analysis using d (no PV Buses)										
9. Optimal g	enerator sch	neduling for thermal power plants.										
Reference B	ooks:											
1. Rudraprat	ap, " Matlał	p getting started with MATLAB", Oxford University press.										
Course out On comple		course, the student will have the ability to:										
Course Code	CO #	Course Outcome (CO)										
21EEL66	CO1	Describe Power System tools of MATLAB, determine Y bus by using inspection and singular transformation.										
	CO2	Determination of Bus Currents, Bus power and line flows for a specified power system networks.										
	CO3	Determination of power angle diagrams for synchronous machines, find fault currents and voltages in a single transmission line system with star delta transformers.										
	CO4	Load flow analysis for a power system network by using Gauss Seidal, Newton Raphson and fast decoupled load flow studies										
	CO5	Determine optimal generator scheduling for thermal power pla	ants									

Course Articulation Matrix for the Academic Year 2022-23

S.No.	РО	1	2	3	4	5	6	7	8	9	10	11	12	PSO1	PSO2	PSO3
	CO															
1	CO1	3	3	3	1	1				2			1	3	2	2
2	CO2	3	3	3	1	1				2			1	3	2	2
3	CO3	3	3	3	1	1				2			1	3	2	2
4	CO4	3	3	3	1	1				2			1	3	2	2
5	CO5	3	3	3	1	1				2			1	3	2	2
		3	3	3	1	1				2			1	3	2	2

	21EE642		CIE: 50								
Number of Lecture Hours/Week	2hrs (Theory)		SEE: 50								
Total Number of Lecture Hours	4	42 5									
Prerequisite: Knowledge	of Analog and dig	gital electronics is	required.								
Course Objectives: 1. To study op-amp & AC A 2.To know about Op-Amp I 3. To understand about Sign 4.To study Multivibrator & 5. To study Active Filter &	Frequency Respon- nal Processing Cin Signal Generator Voltage Regulator	cuits Op-amp No									
	Modules			Teaching Hours							
	Module I										
Basics of OP-amps ar (Introduction, Block diagr voltage follower, High Z capacitor coupled Non-inver Non-inverting amplifier, Ca upper cutoff frequency, cap single polarity supply.	ram & Characte inc Capacitor erting amplifier, H apacitor coupled	ristics), capacitor coupled voltage ligh Zinc capacito inverting amplifie	r coupled follower, or coupled er, setting	9 Hrs							
Op-amps Frequency Res	ponse and Com	pensation: Op-ai	np circuit	8 Hrs							
Op-amps Frequency Res stability, frequency and methods, op-amp circuit ba effects, load capacitance eff	phase response, indwidth, slew ra	frequency com te effects, stray ca	pensating	8 Hrs							
stability, frequency and methods, op-amp circuit ba	phase response, indwidth, slew ra	frequency com te effects, stray ca	pensating	8 Hrs							
stability, frequency and methods, op-amp circuit ba	phase response, indwidth, slew rat fects, circuit stabi Module III its and Op-an Il wave rectifiers, ample and Hold	frequency com te effects, stray ca lity precautions. nps Nonlinear (limiting circuits, circuit, Crossing	Circuits : clamping detectors,	8 Hrs 8 Hrs							
stability, frequency and methods, op-amp circuit ba effects, load capacitance eff Signal Processing Circui Precision half wave and ful circuits, peak detectors, Sa	phase response, indwidth, slew rat fects, circuit stabi Module III its and Op-an Il wave rectifiers, ample and Hold	frequency com te effects, stray ca lity precautions. nps Nonlinear (limiting circuits, circuit, Crossing	Circuits : clamping detectors,								

Active filters &	9 Hrs						
pass, low pass,							
regulator, volta							
voltage regulate	or, IC L	M723.					
Question pape	r patter	rn: Total ten questions will be asked. Two from eac	ch module. The				
student has to a	nswer f	ive questions, selecting at least one from each mode	ule.				
Reference Boo	oks:						
 Linear inte 2004. Operational Education, 	grated of Ampli Fourth H	fiers and Linear IC's by Ramakanth PHI Pearson 4 th circuits by Roy Choudary, New Age Internation fiers with linear integrated circuit by Stanley W Edition, 2009. completion of the course, the student will have t	al second edition, Tilliam D, Pearson				
Course Code	СО	Course Outcome (CO)					
	CO1	Describe the basics of Op-Amps					
	CO2	Calculate the frequency response of Op-Amps and Identify compensation methods of op-amp					
18EE631	CO3	Illustrate different types of signal processing circuit and Non-linear circuits					
	CO4 Design different types of multivibrator as signal generators						
	CO5	Identify and Illustrate the active filters and DC voltage regulators					

S.No.	PO	1	2	3	4	5	6	7	8	9	10	11	12	PSO1	PSO2	PSO3
	CO															
1	CO1	3											1	3		1
2	CO2	3		1									1	3	2	1
3	CO3	3	2										1	3	2	1
4	CO4	3	3										1	3	2	1
5	CO5	3	1										1	3	2	1
		3	2	1									1	3	2	1

	urse Title: Reactiv	ve Power Manag	ement
Course Code	21EE643	Credits:03	CIE: 50
Number of Lecture	2Hrs (Theor	y) + 2(Tutorial)	SEE: 50
Hours/Week			
Total Number of Lecture	4	2	SEE Hours: 03
Hours			
Prerequisite:			
Course Objectives:			
	Modules		Teaching Hours
	Module-I		
Load Compensation: Objectives nductive and capacitive approximation bhase balancing and power fact (08 hours)	ate biasing, Load compe	ensator as a voltage reg	gulator,
	Module-II		
Steady – State Reactive Power Con ine, types of compensation, Passiv examples Transient state reactiv Characteristic time periods, passi capacitor compensation, compensa	ve shunt and series and c ve power compensation, ve shunt compensation,	lynamic shunt comper n in transmission s static compensations	nsation, ystems: , series 09 Hrs
Module-III			
Reactive Power Coordination: Obj ransmission benefits, Basic concep state variations, effects of under v electromagnetic interferences.	pts of quality of power s	upply, disturbances, s	teady –
electromagnetic interferences.	Module-IV		09 Hrs
Demand Side Management: Load p KVAR based tariffs penalties for v			riffs,
Distribution side Reactive power l examples, Reactive power plan placement, retrofitting of capacitor	nning, objectives, Eco		
• ·	Module-V		
User Side Reactive Powe domestic appliances, Purpose deciding factors, types of Limitations.	e of using capacitors	, selection of capa	citors, 08 Hrs
Reactive power manageme furnaces: Typical layout of requirements, distribution to operations, furnaces transform ower factor of an arc furnace Ouestion paper pattern: To	traction systems, ransformers, Electri mer, filter requireme e.	reactive power c ic arc furnaces, ents, remedial mea	ontrol basic
has to answer five questions,	1		
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01. Reactive power control in Electric power systems by T.J.E. Miller, John Wiley and sons, 1982.

02. Reactive power Management by D. M. Tagare, Tata McGraw Hill, 2004. **Reference Books:**

01. Reactive Power Compensation: A Practical Guide, Wolfgang Hofmann, Jurgen Schlabbach, Wolfgang Just, Wiely publication 2012.

02. Reactive Power Compensation, Dr. Hidaia Mahmood Alassouli, Notion Press, 2020 Course outcomes:

On completion of the course, the student will have the ability to:											
Course Code	CO	Course Outcome (CO)	Blooms Level								
	CO1	Distinguish the importance of load compensation in symmetrical as well as unsymmetrical loads									
21EE643	CO2	Observe various compensation methods in transmission lines									
2122043	CO3	Construct model for reactive power coordination									
	CO4	Distinguish demand side reactive power management & user side reactive power management									
	CO5										

S.No.	РО	1	2	3	4	5	6	7	8	9	10	11	12	PSO1	PSO2	PSO3
	CO															
1	CO1	3		2												
2	CO2	3		2	3											
3	CO3	3	3	3												
4	CO4	3	3										3			
5	CO5															